

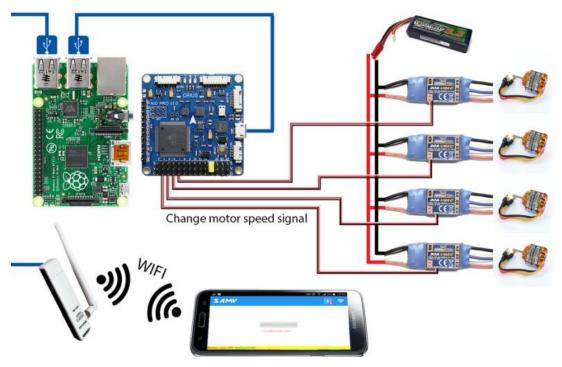
RASPBERRY MICROCONTROLLER DRONE MODEL-DRONE100

This Drone trainer kit has been designed with a view to provide practical and experimental knowledge to make a Drone using Raspberry Micro Controller.

SPECIFICATIONS



Hardware



Connections



Mission Planer - ArduPilot - Software



Radio Transmitter and Fs Ia6 Receiver

1. Drone Hardware

1. Raspberry Micro Controller : Pi 4 Model B

2. NAVIO Kit : with Power module, wires and GPS

3. ESCs : 4 Nos

4. Motors : 4 Nos

5. Frame : 1 No

6. Propeller : 4 Nos

7. Battery : 1 No.

8. Battery Charger : 1 No

9. Telemetry Transmitter Receiver : 1 No

10. LiPo Fire-proof Case : 1 No

11. PPM Encoder : 1 No

12. Micro SD Card : 32 GB

13. Micro SD to USB Reader : 1 No

14. Battery Connector : 4 Nos

15. GPS Mount : 1 No

16. Velcro Straps : 1 No

17. Scotch Mounting Tape : 1 No

18. Zip Ties : 10 Nos

19. Allen Wrench : 1 No

20. Electrical Tape : 1 No

21. Flight Controller - RC Controller : 1 No

2. Software:

- 1. Python 3.11
- 2. ArduPilot

3. Accessories:

1. Pen Derive with Software, Library, Driver,

Codes, Soft Copy of Manual and Mobile App : 16 GB

2. Printed Practical Manual : 1 No.

3. E-Books for IOT Subject : 10 Nos. in PDF Format

4. Mp4 Video Class for Drone : 40 Nos

4. Cabinet and PCB

The complete circuit diagram is screen printed on component side of the PCB with circuit and Parts at the same place. The PCB with components on front side is fitted in elegant wooden box having lock and key arrangement. The acrylic cover is fitted on PCB to safeguard parts. It works on 230 V AC Supply.

EXPERIMENTS

A. Theory Experiments

- 1. To understand theory and working of Drone
- 2. To understand theory and working of Block Diagram of Drone System
- 3. To understand theory and working of Raspberry Micro Controller
- 4. To understand theory and working of Flight Controller
- To understand theory and working of Electronic Speed Controller ESC
- 6. To understand theory and working of Distribution board
- 7. To understand theory and working of Battery used in Drone System
- 8. To understand theory and working of Propeller
- 9. To understand theory and working of Motors used in Drone system
- 10. To understand Software used for Drone System
- 11. To understand theory and working of Remote Controller RC

B. Drone Assembly Experiments

- 1. To solder the bullet connectors onto the ESCs
- 2. To solder ESCs to the distribution board and soldering battery connector to board
- 3. To attach Drone arms to bottom plate
- 4. To install motors onto the frame
- 5. To install RC Controller onto Raspberry Pi and install them onto the top plate
- 6. To install top plate to the Drone
- 7. To fix ESCs to frame securely
- To bind Controller / Transceiver / Transmitter with the Receiver
- 9. To calibrate the ESCs
- 10. To check motors spin direction
- 11. To attach PPM encoder and RC receiver to the Drone
- 12. To connect ESCs to the RC Controller
- 13. To attach and connect Telemetry Transmitter Receiver Module to the Drone
- 14. To attach Power module to Drone
- 15. To attach landing gear
- 16. To build GPS mount and attach GPS Antenna onto it
- 17. To protect the barometer from UV radiation
- 18. To attach Propellers
- 19. To protect all electrical connections with electrical tape
- 20. To attach charged battery with velcro strap

C. Drone Software and Testing Experiments

- 1. To install Python program
- 2. To install Drone controlling Software ArduPilot
- 3. To SSH to NAVIO2 to power source and run the emlidtool command
- 4. To familiarize Arducopter
- 5. To control Drone using Remote Controller
- 6. To control Drone using Python Program

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